

# AIRSPACE INTEGRATION

ENABLING SCALABLE, EFFICIENT, AND SAFE ACCESS TO AIRSPACE

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# CURRENT AIRSPACE OPERATIONS



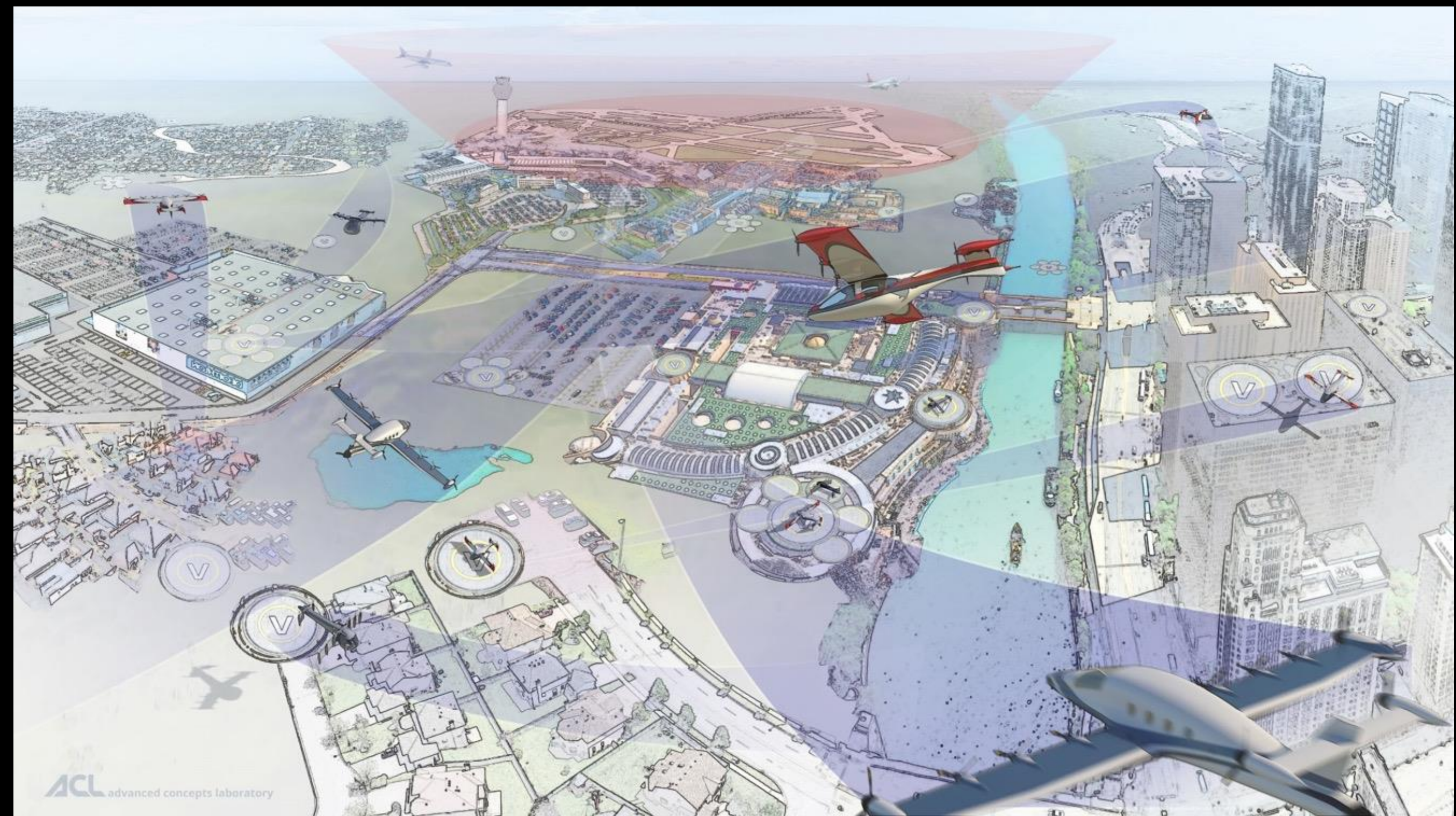


# SMALL UNMANNED AIRCRAFT SYSTEMS





# VERTICAL TAKE OFF AND LANDING (VTOLS)



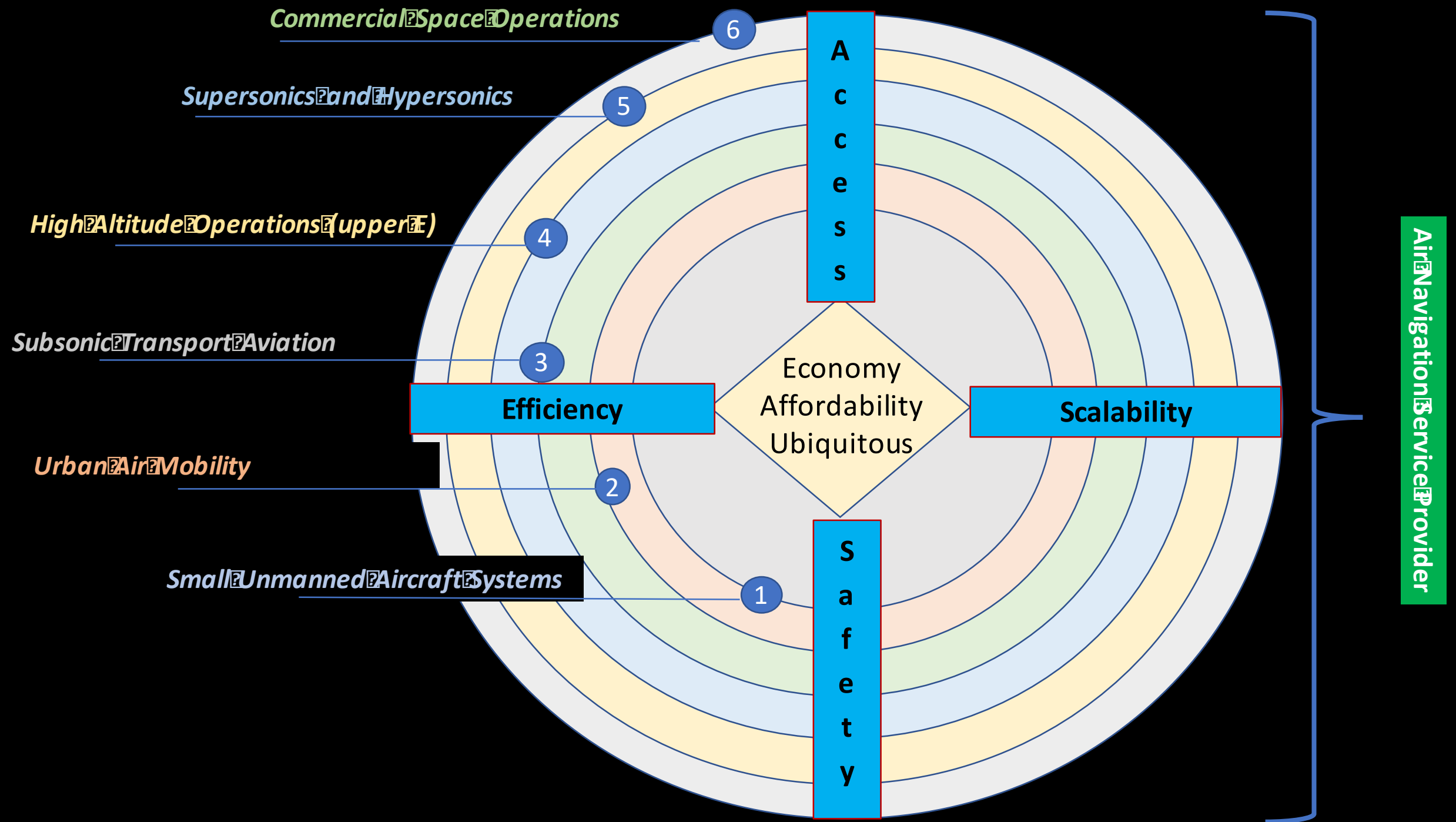


# URBAN AIR MOBILITY: SMALL DRONES TO LARGER PASSENGER CARRYING VTOLS



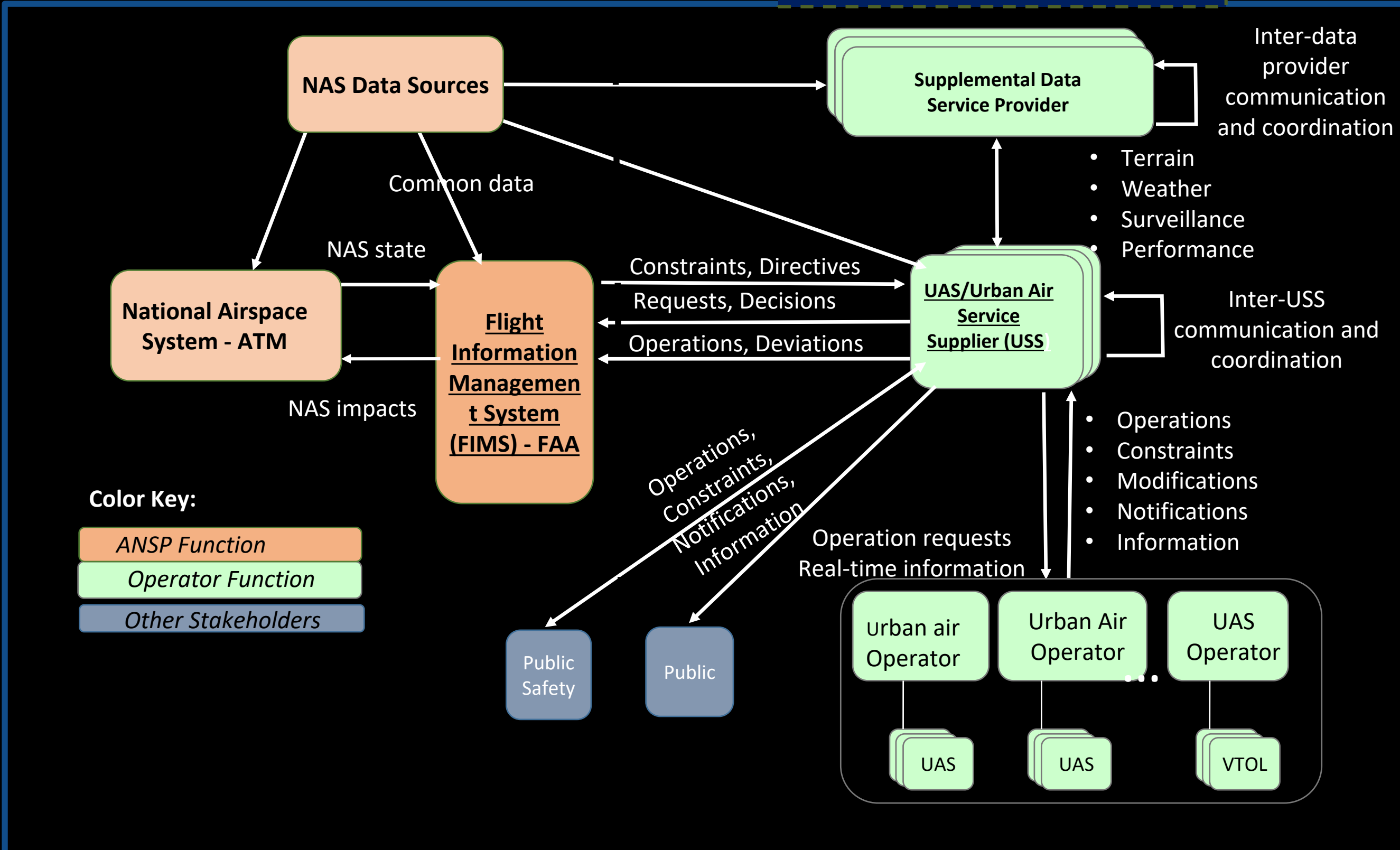


# AIRSPACE USER TYPES ARE INCREASING



# BASIC ARCHITECTURE

## Extension of UAS Traffic Management



# URBAN AIR MOBILITY AIRSPACE INTEGRATION PRINCIPLES

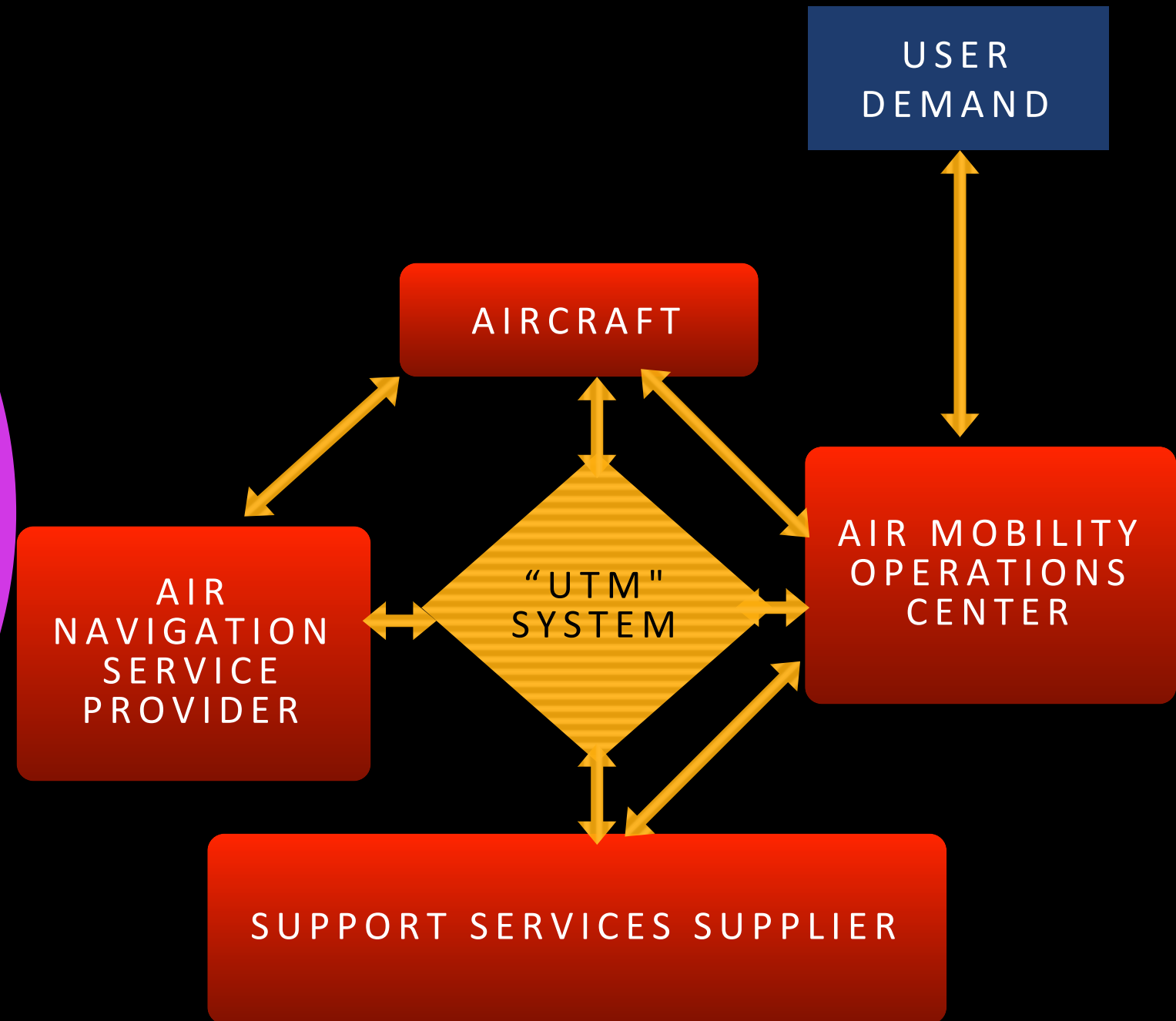
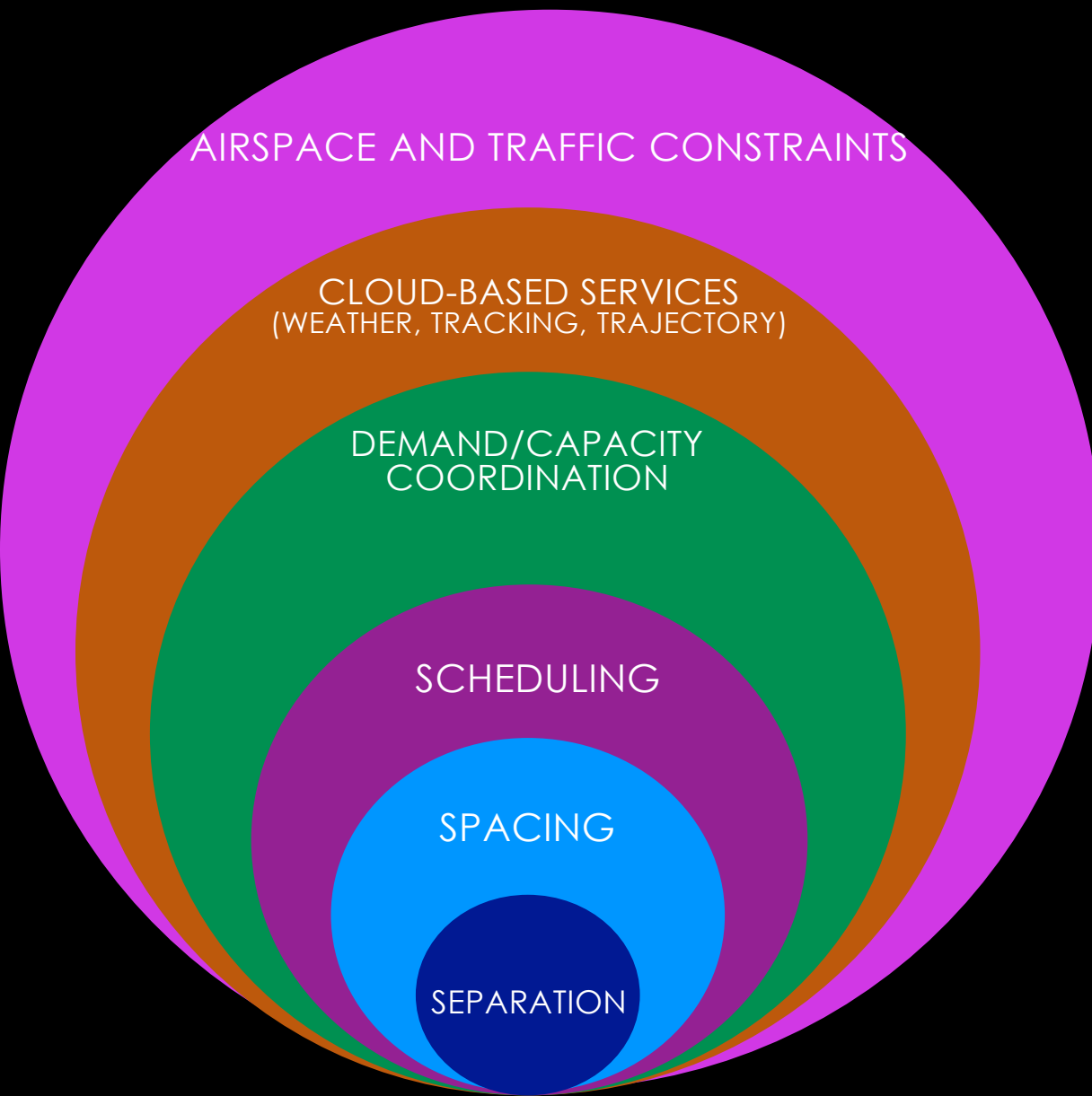
- No burden on current system
- Cooperative and interoperable with other users
- Performance and risk-based
- Efficient
- Safe
- Scalability and sustainability



BUILD ON THE FOUNDATION OF  
UNMANNED AIRCRAFT SYSTEM TRAFFIC MANAGEMENT (UTM)

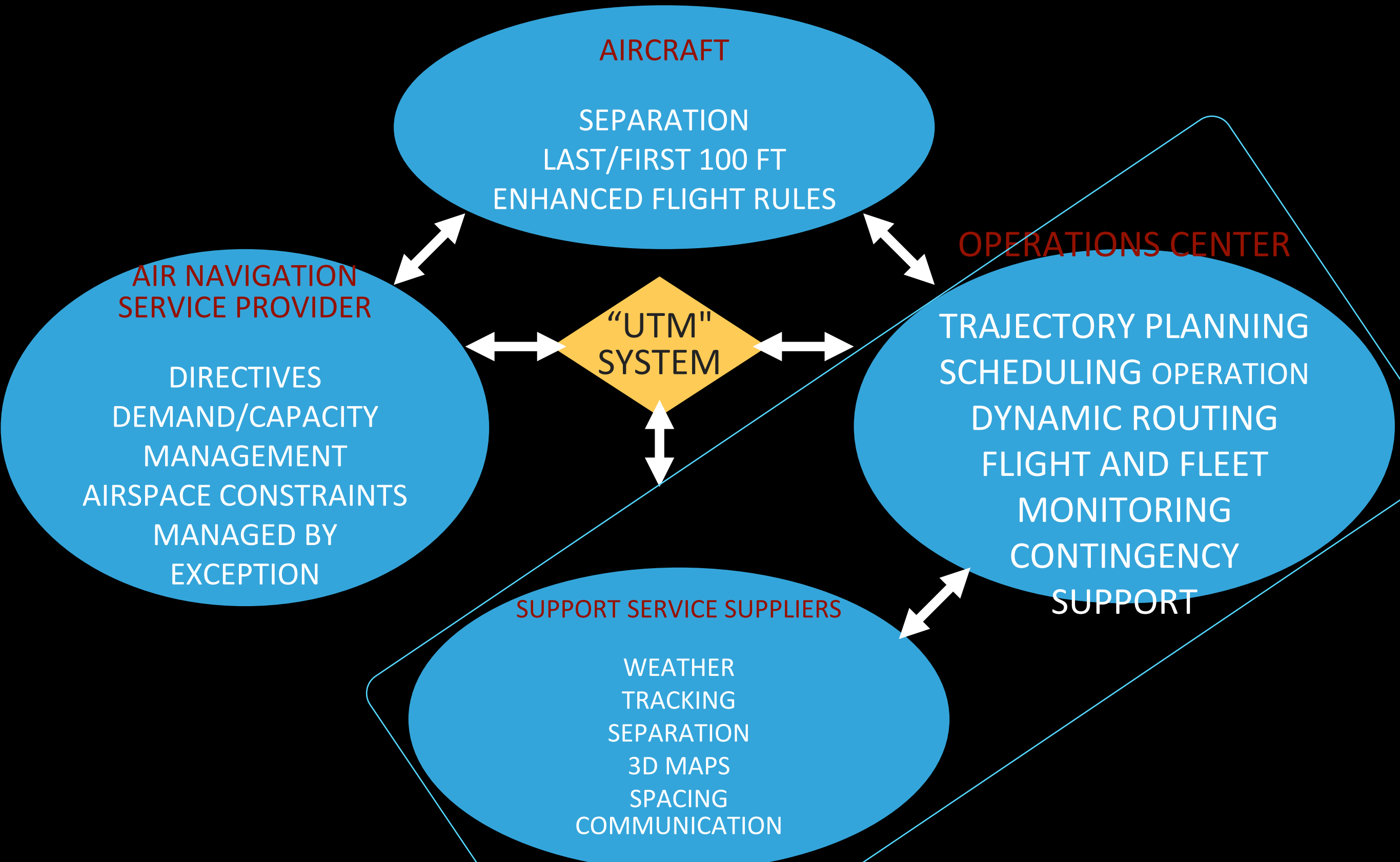


# CONNECTED SYSTEM FOR SCALABILITY





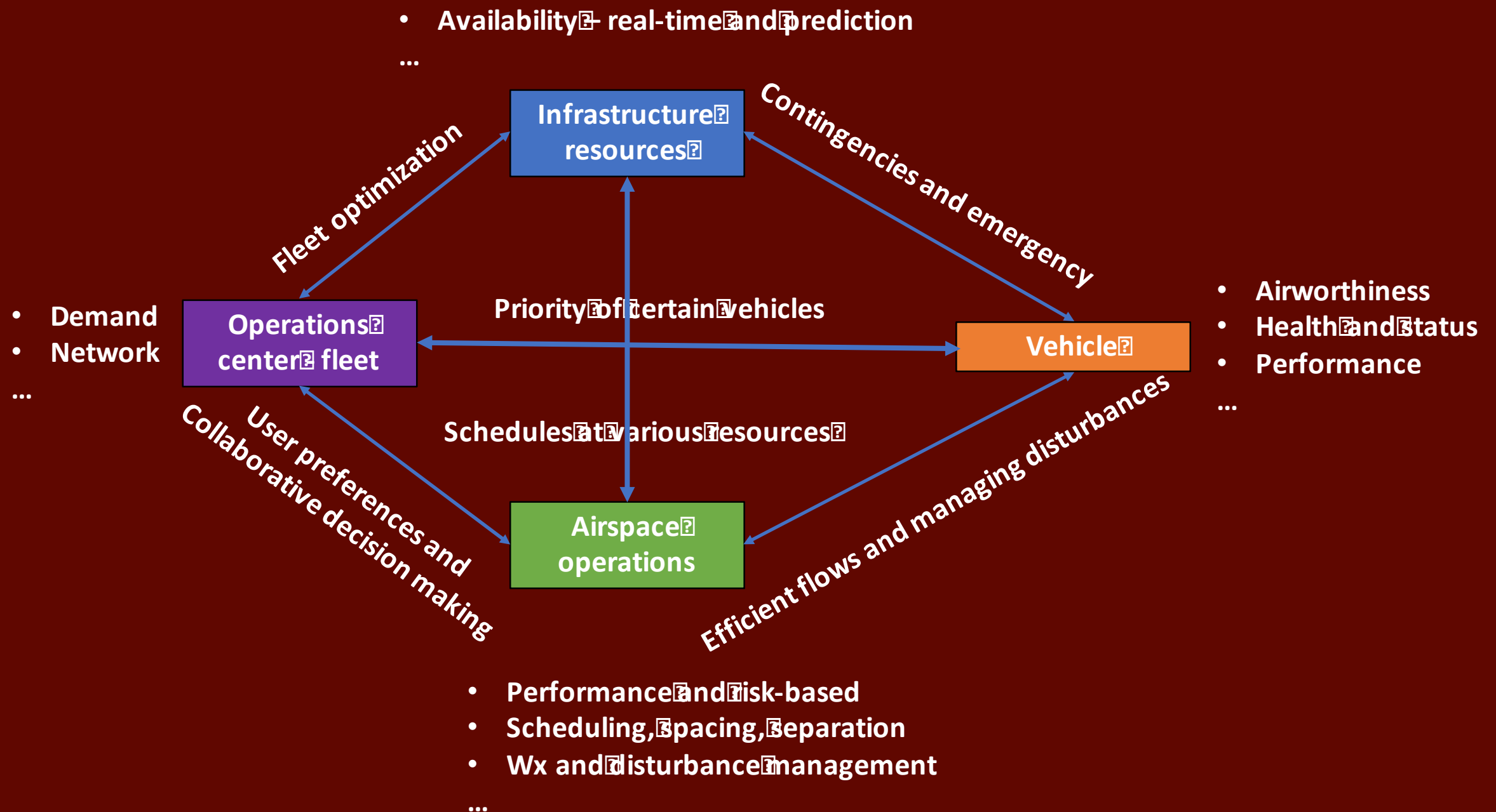
FLEXIBILITY WHERE POSSIBLE, STRUCTURE WHERE NECESSARY



RESEARCH TO DETERMINE SERVICES, PERFORMANCE NEEDS, AUTOMATION CAPABILITIES FOR SCALED OPERATIONS



# CONNECTIVITY IS KEY



**Autonomy alone will not lead to efficiency and large-scale disturbance management**  
**Connectivity is crucial - air/ground/cloud/infrastructure integration will be key**



EMBRACING INNOVATION IN  
AVIATION WHILE RESPECTING ITS  
SAFETY TRADITION

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# UTM STYLE AIRSPACE OPERATIONS ENVIRONMENT

- **Cooperative**
- **Intent-sharing**
- **Digital: data exchanges among operators**
- **Standardized application protocol interfaces**
- **Air/ground integrated**
- **Service-oriented architecture**
- **Role for third parties**

**Space Traffic Management**

**High Altitude UTM (upper E)**

**Conventional Manned Aviation  
(Class A, B, C, D, E)**

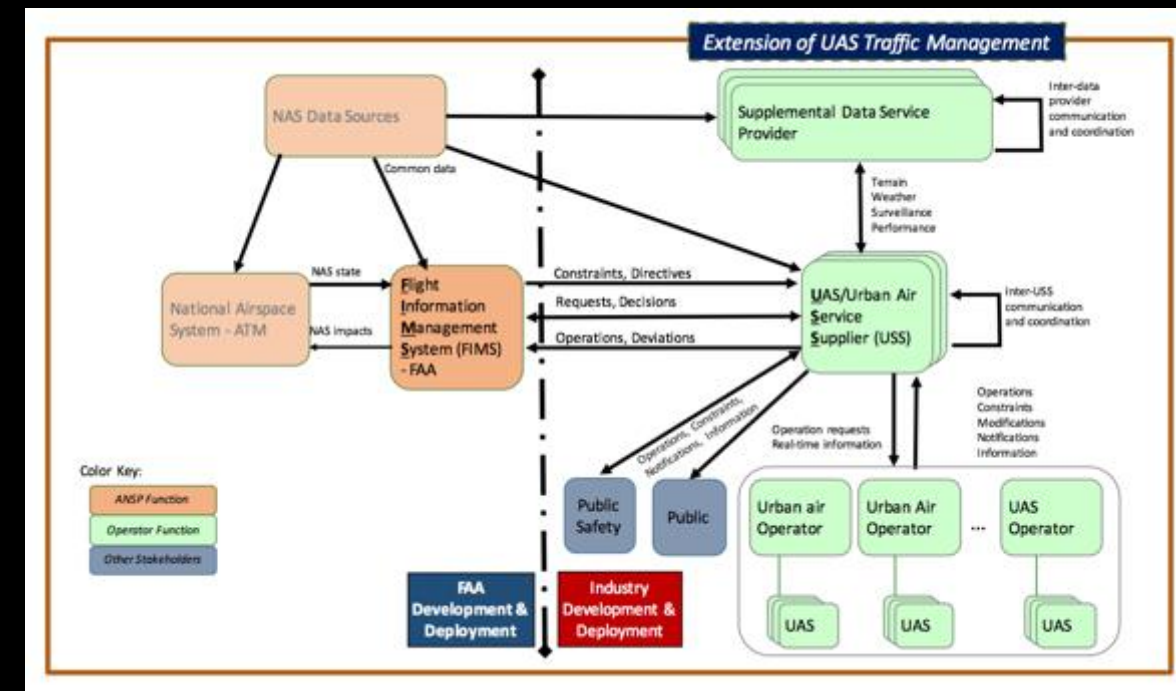
**Urban Air Mobility**

**Low-altitude small UAS**



# PATH FOR SCALABILITY

- Architecture, roles/responsibilities and technology that allows self-management as much as possible
- Air traffic control interacts indirectly for the majority of flight - for constraints and directives, and airspace changes
- Operator plans and schedules operation through UTM
- Tracking via wireless, satellite, ADS-B, or beacon-based systems connected through UTM
- Air-ground-cloud integrated system for scalability (spacing, separation, flow management, etc)
- Last/first 100 feet for safe and automated take-off and landing
- Vertiport design and operations for multiple simultaneous arrivals and departures





# CRAWL-WALK-RUN APPROACH

## Low-density: Initial Operational Capability

- Helicopter routes using today's procedures
- Entry into controlled airspace thru UTM
- Users: conflict-free trajectories and own tracking



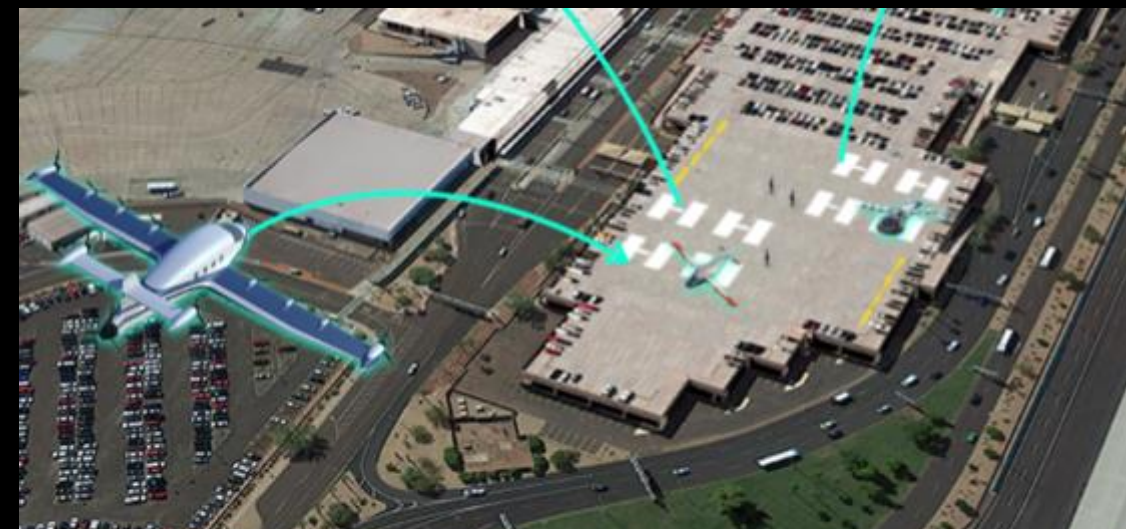
## Medium-density: Interim Operational Capability

- User creates conflict-free trajectories
- Interoperable, cooperative, and intent sharing
- Self-managed operations



## High-density: Mature Operational Capability

- Fully-autonomous planning, scheduling, separations, entry/exit controlled airspace, interoperability, and contingency management
- Multiple, simultaneous take-offs and landings



# RESEARCH

- Scalable en route and arrival/departure operations
- Cooperative and interoperable operations
- Design of vertiports with multiple vertipads
- Weather tolerant operations (75% delays are due to Wx)
- Off-nominal conditions and contingency operations
  - High winds, wind shears, up drafts, etc.
  - Power depletion
  - Bird strikes
- Requirements (e.g. reserve fuel)
- Integrated air/ground/cloud/infrastructure connected system